

# Rukun (Eric) Qiao

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# Machine Learning Engineer

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## Profile

**Hands-on machine learning engineer** with end-to-end experience in robotics and 3D vision. **PhD research** centered on multi-view 3D reconstruction, sensor fusion, and deep learning for geometric perception, specialized in **predictive modeling and transformer model for data-driven decision making**. **Strong software engineering skills** across algorithms, application development, and data workflows; write clean, maintainable code and deliver reliably with testing and automation. **Full-stack developing experience** to move ideas from prototype to production. **Proactive engineer with an analytical mindset** who turns ambiguous problems into clear metrics, dashboards, and experiments, and communicates insights to guide data-driven decisions. **Passionate about using data and machine learning to deliver measurable improvements in business performance and user experience**.

## Technical Skills

- **Languages:** Python, JavaScript, C++, C#, Java
- **GenAI:** LLMs, Retrieval-Augmented Generation (RAG)
- **Machine Learning:** PyTorch, TensorFlow, Scikit-learn
- **Data Platform:** PostgreSQL, VectorDB, Databricks, Snowflake, Spark
- **Experimentation:** A/B Test, Power Analysis, Statistic Tests
- **Full-stack Development:** React, Node.js, RESTful APIs, GraphQL
- **DevOps & Cloud:** Git, Docker, Github Actions, Azure, AWS
- **Data Visualization:** PowerBI, Matplotlib, Seaborn, MATLAB, OpenCV, Open3D

## Soft Skills

- Agile development
- Ownership mindset
- Learning agility
- Problem solving
- Coaching & mentoring
- Analytical mindset
- Business argument

## Education

### Peking University | PhD in Artificial Intelligence

QS World University Rankings #14 | School of Intelligence Science and Technology

Beijing, China

Sep. 2016 – Jul. 2024

### Peking University | BSc in Artificial Intelligence

School of Electronic Engineering and Computer Science

Beijing, China

Sep. 2012 – Jul. 2016

### Kyushu University | Visiting Scholar Program

Graduate School of Information Science and Electrical Engineering

Fukuoka, Japan

Sep. 2018 – Mar. 2019

## Professional Experience

### Machine Learning Engineer | Yureca Technology

Oct. 2024 – Now

Tech Stack: React Native, FastAPI, PostgreSQL, Github Actions, Azure, AWS, LLMs, RAG, VectorDB

- **Led the development of an end-to-end household inventory management system**, delivering data-driven insights through automated recommendations and reports.
- **Engineered a production-ready full-stack architecture** across mobile front end, backend services, and PostgreSQL persistence, with JIRA-managed agile delivery.
- **Developed machine learning models to learn user consumption patterns and item features**, enabling purchase cycle prediction, restock recommendations, and automatic item annotation, with **online adaptation via user behavior tracking and CI/CD pipelines**.
- **Implemented GenAI and RAG pipelines** to support natural language item entry and proactive, context-aware recommendations based on user inventory state.
- **Designed ETL pipelines, dashboards, and periodic reports**, integrating backend metrics to monitor system performance, resource usage, and cost efficiency.

## Software Engineer | CLCN

Mar. 2025 – Now

Tech Stack: *React Vite, Node.js, Figma, Github Actions*

- Contribute to the **front-end development of an internal ERP web app** that creates a transparent, measurable collaboration framework and standardizes handoffs.
- Transform manual processes into **automated, step-based workflows** that deliver guidance, progress tracking, and reminders, aligned with clear UI flows/specs defined by business and design teams.
- Build collaboration features around volunteer profiles and availability** so organizers can assemble teams, send invitations, and coordinate tasks transparently.
- Establish **unit and component tests for critical flows**, define QA checklist and regression suites.
- Instrument **data capture with data tracking** to support post-event reviews and training, laying the foundation for analytics-driven improvements and policy updates.

*Before the completion of PhD*

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## Machine Learning Engineer | SenseTime

Sep. 2020 – Sep. 2021

Tech Stack: *Python, PyTorch, OpenCV, NumPy, CUDA, Git, Docker*

- Built an automated multi-sensor data pipeline for **mobile 3D capture**, including standardizing images, time-aligning IMU data, and extracting features, to power downstream 3D reconstruction models.
- Acted as a professional consultant, engaging stakeholders for **requirement collection and success-metric alignment, setting acceptance thresholds and release gates to app performance**.
- Developed a **deep-learning multi-view model** to reduce reconstruction uncertainty, and enabled a **post-deployment fine-tuning loop** on user-returned images.
- Optimized inference efficiency by integrating classical 3D matching algorithms with deep learning models, **reducing computational load for mobile deployment**.
- Delivered the solution as a modular Python package with clear docs and tests**, and exposed a lightweight REST/HTTP wrapper to streamline integration with the mobile app and internal tooling, enabled downstream 3D-model-based features.

## Computer Vision Engineer | BOE Technology

Sep. 2018 – Sep. 2019

Tech Stack: *C++, OpenCV, MATLAB, ROS*

- Coordinated cross-functional teams to develop a **visual navigation system for autonomous cleaning robots**, aligning perception, planning and hardware modules.
- Installed and calibrated stereo cameras and supportive sensors, performing intrinsic and extrinsic calibration to **achieve sub-millimetre pose estimation accuracy in production environments**.
- Implemented **C++ modules for real-time sensor data acquisition and preprocessing**, improving data reliability under varying lighting conditions, integrated into the commercial cleaning-robot line.
- Produced technical documentation and conducted workshops to help engineering and operations teams **interpret system outputs and safely adjust parameters** for different deployment scenarios.

## Research Achievements

PhD research in **robotics and 3D perception**, with a focus on modeling **uncertainty in real-world sensor data**. Designed efficient deep learning methods that balance **accuracy, robustness, and computational cost**, enabling reliable perception under practical system constraints.

## Publications

- Rukun Qiao**, Hiroshi Kawasaki and Hongbin Zha, "TIDE: Temporally Incremental Disparity Estimation via Pattern Flow in Structured Light System," in *IEEE Robotics and Automation Letters*, pp.5111-5118, April 2022.
- Rukun Qiao**, Hiroshi Kawasaki and Hongbin Zha, "Online Adaptive Disparity Estimation for Dynamic Scenes in Structured Light Systems," in *IEEE/RSJ International Conference on Intelligent Robotics and Systems*, 2023.
- Rukun Qiao**, Hiroshi Kawasaki and Hongbin Zha, "Depth Estimation in Structured Light Systems via Neural Implicit Functions," in *International Conference on 3D Vision*, 2024.